

A 6-DIMENSIONAL SIMPLY CONNECTED COMPLEX AND SYMPLECTIC MANIFOLD WITH NO KÄHLER METRIC

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ABSTRACT. We construct a simply connected compact manifold which has complex and symplectic structures but does not admit Kähler metric, in the lowest possible dimension where this can happen, that is, dimension 6. Such a manifold is automatically formal and has even odd-degree Betti numbers but it does not satisfy the Lefschetz property for any symplectic form.

1. INTRODUCTION

A Kähler manifold (M, J, ω) is a smooth manifold M of dimension $2n$ endowed with an integrable almost complex structure J and a symplectic form ω such that $g(X, Y) = \omega(X, JY)$ defines a Riemannian metric, called *Kähler metric*. In order to check that a compact manifold does not carry any Kähler metric, one can use a collection of known topological obstructions to the existence of such a structure: theory of Kähler groups, evenness of odd-degree Betti numbers, Lefschetz property or the formality of the rational homotopy type (see [1, 7, 23]).

If M is a compact Kähler manifold, then it has a complex and a symplectic structure. However, the converse is not true. The first example of a compact manifold admitting complex and symplectic structures but no Kähler metric is the Kodaira-Thurston manifold [16, 21]. This 4-manifold is not simply connected (it is actually a nilmanifold) hence the fundamental group plays a key role in this property. The classification of complex and symplectic nilmanifolds of dimension 6 was given by Salamon in [20]. Generalizations to higher dimension $2n \geq 6$ of the Kodaira-Thurston manifold are the generalized Iwasawa manifolds considered in [6]. Such manifolds have complex and symplectic structures but carry no Kähler metric. Note that, in dimension 2, every oriented surface admits a Kähler metric.

If one restricts attention to manifolds with trivial fundamental group, then every complex manifold of real dimension 4 admits a Kähler structure. Indeed, by the Enriques-Kodaira classification [16], if M is a complex surface whose first Betti number b_1 is even (this holds in particular when $b_1 = 0$), then M is deformation equivalent to a Kähler surface (see also [2, Theorem 3.1, page 144] for a direct proof of this fact). We point out that Gompf [13] has constructed the first examples of simply connected compact symplectic but not complex 4-manifolds. Also Fintushel and Stern [12] have given a family of simply connected symplectic 4-manifolds not admitting complex structures (the latter was proved by Park [19]).

In dimensions higher than 4, we have the following results. The first examples of simply connected compact symplectic non-Kählerian manifolds were given in dimension 6 by Gompf in the aforementioned paper [13] and in dimension ≥ 10 by McDuff in [17] (these examples are not known to admit complex structures). Fine and Panov in [10] (see also [11]) have produced

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simply connected symplectic 6-manifolds with $c_1 = 0$ which do not have a compatible complex structure (but it is not known if they admit Kähler structures). Furthermore, Guan in [14] constructed the first family of simply connected, compact and holomorphic symplectic non-Kählerian manifolds of (real) dimension $4n \geq 8$. On the other hand, the first and third authors have proved [3] that the 8-dimensional manifold X constructed in [9] is an example of a simply connected, symplectic and complex manifold which does not admit a Kähler structure (since it is not formal). For higher dimensions $2n = 8 + 2k$, $k \geq 1$, one can take $X \times \mathbb{C}\mathbb{P}^k$. This is simply connected, complex and symplectic but not Kähler. Thus, a natural question arises:

Does there exist a 6-dimensional simply connected, compact, symplectic and complex manifold which does not admit Kähler metrics?

In this paper we answer this question in the affirmative by proving the following result:

Theorem 1.1. *There exists a 6-dimensional, simply connected, compact, symplectic and complex manifold which carries no Kähler metric.*

In order to construct such an example, we start with a 6-dimensional nilmanifold M admitting both a complex structure J and a symplectic structure ω . Then we quotient it by a finite group preserving J and ω to obtain a simply connected, 6-dimensional orbifold \widehat{M} with an orbifold complex structure \widehat{J} and an orbifold symplectic form $\widehat{\omega}$. By Hironaka Theorem [15], there is a complex resolution $(\widetilde{M}_c, \widetilde{J})$ of $(\widehat{M}, \widehat{J})$. As in [5], we resolve symplectically the singularities of $(\widehat{M}, \widehat{\omega})$ to obtain a smooth symplectic 6-manifold $(\widetilde{M}_s, \widetilde{\omega})$. However, in our situation, the singular locus of the orbifold \widehat{M} does not consist only of a discrete set of points, in contrast with [5]. For a complex and symplectic orbifold, we provide conditions under which the complex and the symplectic resolution of singularities are diffeomorphic (Theorem 3.1). Using this we prove that the resolutions \widetilde{M}_c and \widetilde{M}_s are diffeomorphic. Thus, $\widetilde{M} = \widetilde{M}_c$ is not only a complex manifold but also a symplectic one.

Next, we show that \widetilde{M} is simply connected (Proposition 6.1), this resulting from the careful choice of the action of the finite group on M . Since \widetilde{M} is a 6-dimensional simply connected compact manifold, then $b_1(\widetilde{M}) = 0$, and $b_3(\widetilde{M})$ is even by Poincaré duality. Also \widetilde{M} is automatically formal by [8, Theorem 3.2]. Therefore, to ensure that \widetilde{M} does not carry any Kähler metric, we use the Lefschetz property; more precisely, we prove that the map $L_{[\Omega]}: H^2(\widetilde{M}) \rightarrow H^4(\widetilde{M})$ given by the cup product with $[\Omega]$ is not an isomorphism for any possible symplectic form Ω . Again the choice of nilmanifold M and finite group action makes possible to have a non-zero $[\beta] \in H^2(\widetilde{M})$ such that $[\beta] \wedge [\alpha_1] \wedge [\alpha_2] = 0$ for every $[\alpha_1], [\alpha_2] \in H^2(\widetilde{M})$, which gives the result.

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2. ORBIFOLDS

Definition 2.1. A (smooth) n -dimensional orbifold is a Hausdorff, paracompact topological space X endowed with an atlas $\mathcal{A} = \{(U_p, \tilde{U}_p, \Gamma_p, \varphi_p)\}$ of orbifold charts, that is $U_p \subset X$ is a neighbourhood of $p \in X$, $\tilde{U}_p \subset \mathbb{R}^n$ an open set, $\Gamma_p \subset \text{GL}(n, \mathbb{R})$ a finite group acting on \tilde{U}_p , and $\varphi_p: \tilde{U}_p \rightarrow U_p$ is a Γ_p -invariant map with $\varphi_p(0) = p$, inducing a homeomorphism $\tilde{U}_p/\Gamma_p \cong U_p$.

The charts are compatible in the following sense: if $q \in U_q \cap U_p$, then there exist a connected neighbourhood $V \subset U_q \cap U_p$ and a diffeomorphism $f: \varphi_p^{-1}(V)_0 \rightarrow \varphi_q^{-1}(V)$, where $\varphi_p^{-1}(V)_0$ is the connected component of $\varphi_p^{-1}(V)$ containing q , such that $f(\sigma(x)) = \rho(\sigma)(f(x))$, for any x , and $\sigma \in \text{Stab}_{\Gamma_p}(q)$, where $\rho: \text{Stab}_{\Gamma_p}(q) \rightarrow \Gamma_q$ is a group isomorphism.

For each $p \in X$, let $n_p = \#\Gamma_p$ be the order of the orbifold point (if $n_p = 1$ the point is smooth, also called non-orbifold point). The singular locus of the orbifold is the set $S = \{p \in X \mid n_p > 1\}$. Therefore $M - S$ is a smooth n -dimensional manifold. The singular locus S is stratified: if we write $S_k = \{p \mid n_p = k\}$, and consider its closure $\overline{S_k}$, then $\overline{S_k}$ inherits the structure of an orbifold. In particular S_k is a smooth manifold, and the closure consists of some points of S_{kl} , $l \geq 2$.

We say that the orbifold is locally oriented if $\Gamma_p \subset \text{GL}_+(n, \mathbb{R})$ for any $p \in X$. As Γ_p is finite, we can choose a metric on \tilde{U}_p such that $\Gamma_p \subset \text{SO}(n)$. An element $\sigma \in \Gamma_p$ admits a basis in which it is written as $\sigma = \text{diag} \left(\begin{pmatrix} \cos \theta_1 & -\sin \theta_1 \\ \sin \theta_1 & \cos \theta_1 \end{pmatrix}, \dots, \begin{pmatrix} \cos \theta_r & -\sin \theta_r \\ \sin \theta_r & \cos \theta_r \end{pmatrix}, 1, \dots, 1 \right)$, for $\theta_1, \dots, \theta_r \in (0, 2\pi)$. In particular, the set of points fixed by σ is of codimension $2r$. Therefore the set of singular points $S \cap U_p$ is of codimension ≥ 2 , and hence $X - S$ is connected (if X is connected). Also we say that the orbifold X is oriented if it is locally oriented and $X - S$ is oriented.

A natural example of orbifold appears when we take a smooth manifold M and a finite group Γ acting on M effectively. Then $\widehat{M} = M/\Gamma$ is an orbifold. If M is oriented and the action of Γ preserves the orientation, then \widehat{M} is an oriented orbifold. Note that for every $\widehat{p} \in \widehat{M}$, the group $\Gamma_{\widehat{p}}$ is the stabilizer of $p \in M$, with $\widehat{p} = \widehat{\pi}(p)$ under the natural projection $\widehat{\pi}: M \rightarrow \widehat{M}$.

Definition 2.2. A complex orbifold is a $2n$ -dimensional orbifold X whose orbifold charts have $\tilde{U}_p \subset \mathbb{C}^n$, $\Gamma_p \subset \text{GL}(n, \mathbb{C})$, and in the compatibility of charts the maps f are biholomorphisms. Note that X is automatically oriented.

If M is a complex manifold and Γ is a finite group acting effectively on M by biholomorphisms, then $\widehat{M} = M/\Gamma$ is a complex orbifold.

The complex structure of a complex orbifold X can be given by the orbifold $(1, 1)$ -tensor J with $J^2 = -\text{Id}$. This is given by tensors J_p on each \tilde{U}_p defining the complex structure, which are Γ_p -equivariant, for each $p \in X$, and which agree under the functions f defining the compatibility of charts.

Definition 2.3. A complex resolution of a complex orbifold (X, J) is a complex manifold \tilde{X} together with a holomorphic map $\pi: \tilde{X} \rightarrow X$ which is a biholomorphism $\tilde{X} - E \rightarrow X - S$, where $S \subset X$ is the singular locus and $E = \pi^{-1}(S)$ is the exceptional locus.

Let X be an orbifold. An orbifold k -form α consists of a collection of k -forms α_p on each \tilde{U}_p which are Γ_p -equivariant and that match under the compatibility maps between different charts.

Definition 2.4. *A symplectic orbifold (X, ω) consists of a $2n$ -dimensional oriented orbifold X and an orbifold 2-form ω such that $d\omega = 0$ and $\omega^n > 0$ everywhere.*

If M is a symplectic manifold and Γ is a finite group acting effectively on M by symplectomorphisms, then $\widehat{M} = M/\Gamma$ is a symplectic orbifold.

Definition 2.5. *A symplectic resolution of a symplectic orbifold (X, ω) consists of a smooth symplectic manifold $(\tilde{X}, \tilde{\omega})$ and a map $\pi: \tilde{X} \rightarrow X$ such that:*

- π is a diffeomorphism $\tilde{X} - E \rightarrow X - S$, where $S \subset X$ is the singular locus and $E = \pi^{-1}(S)$ is the exceptional locus.
- $\tilde{\omega}$ and $\pi^*\omega$ agree in the complement of a small neighbourhood of E .

3. DESINGULARIZATION OF ORBIFOLD POINTS

In this section we suppose that X is an oriented orbifold whose singular locus S consists of a discrete set of points. Assume that X admits a complex structure J and a symplectic structure ω . Therefore we have a complex orbifold (X, J) and a symplectic orbifold (X, ω) .

It is well-known that (X, J) admits a complex resolution (\tilde{X}_c, \tilde{J}) by Hironaka's desingularization [15]. Also, the symplectic orbifold (X, ω) admits a symplectic resolution $(\tilde{X}_s, \tilde{\omega})$ by Theorem 3.3 in [5]. We want to compare the two resolutions.

First, let us look at the complex resolution of (X, J) . Consider $p \in S$, and let $U_p = \tilde{U}_p/\Gamma_p$ be an orbifold neighbourhood. Recall that we denote $\varphi_p: \tilde{U}_p \rightarrow U_p$ the quotient map. By definition of complex orbifold, $\tilde{U}_p \subset \mathbb{C}^n = \mathbb{R}^{2n}$ and $\Gamma_p \subset \text{GL}(n, \mathbb{C})$. As Γ_p is a finite group, we can choose a Kähler metric invariant by Γ_p . With a linear change of variables, we can transform the Kähler metric into standard form. That is, we can suppose that there is an inclusion

$$(1) \quad \iota: \Gamma_p \hookrightarrow \text{U}(n).$$

Shrinking \tilde{U}_p if necessary, we can assume that $\tilde{U}_p = B_\epsilon(0)$, for some $\epsilon > 0$.

Consider now an algebraic resolution of the singularity of $Y = \mathbb{C}^n/\Gamma_p$, provided by [15]. Denote it $\pi: \tilde{Y} \rightarrow Y$, and let $E = \pi^{-1}(p)$ be the exceptional locus. Write $B = B_\epsilon(0)/\Gamma_p$ and $\tilde{B} = \pi^{-1}(B)$. The complex resolution is defined as the smooth manifold

$$\tilde{X}_c = (X - \{p\}) \cup_\pi \tilde{B},$$

where we identify with the map $\pi: \tilde{B} - E \rightarrow B - \{p\} = U_p - \{p\}$. This has a natural complex structure since π is a biholomorphism.

Now we move to the construction of the symplectic resolution of (X, ω) , as done in [5]. For $p \in S$, take an orbifold neighbourhood $U'_p = \tilde{U}'_p/\Gamma'_p$, with $\varphi'_p: \tilde{U}'_p \rightarrow U'_p$. By the equivariant Darboux theorem, there is a Γ'_p -equivariant symplectomorphism $(\tilde{U}'_p, \omega_p) \cong (V, \omega_0)$, where $V \subset \mathbb{R}^{2n}$ is an open set, and ω_0 is the standard symplectic form (shrinking \tilde{U}'_p if necessary). So without loss of generality, we can assume that $\tilde{U}'_p \subset (\mathbb{R}^{2n}, \omega_0)$, where ω_0 is the standard

symplectic form, and $\Gamma'_p \subset \mathrm{Sp}(2n, \mathbb{R})$. As Γ'_p is a finite group, and $\mathrm{U}(n) \subset \mathrm{Sp}(2n, \mathbb{R})$ is the maximal compact subgroup, we can choose a complex structure J on \mathbb{R}^{2n} such that the pair (J, ω_0) determines a Kähler metric, which is invariant by Γ'_p . We perform a linear change of variables, which transforms the complex structure into standard form (so \tilde{U}'_p has the standard Kähler structure). Equivalently, we can suppose that there is an inclusion

$$(2) \quad \iota': \Gamma'_p \hookrightarrow \mathrm{U}(n).$$

Shrinking \tilde{U}'_p if necessary, we can assume that $\tilde{U}'_p = B_{\epsilon'}(0)$, for some $\epsilon' > 0$.

Consider an algebraic resolution of singularities of $Y' = \mathbb{C}^n/\Gamma'_p$, say $\pi': \tilde{Y}' \rightarrow Y'$, and let $E' = (\pi')^{-1}(p)$ be the exceptional locus. Write $B' = B_{\epsilon'}(0)/\Gamma'_p$ and $\tilde{B}' = (\pi')^{-1}(B')$. The symplectic resolution is defined as the smooth manifold

$$\tilde{X}_s = (X - \{p\}) \cup_{\pi'} \tilde{B}',$$

where $\tilde{B}' - E'$ and $B' - \{p\} = U'_p - \{p\}$ are identified by π' . This has a symplectic structure that is constructed by gluing the symplectic structure of $X - \{p\}$ and the Kähler form of \tilde{B}' by a cut-off process, as done in Theorem 3.3 of [5].

Now we are going to compare \tilde{X}_c and \tilde{X}_s . First note that for $p \in S$, we have $\Gamma_p \cong \Gamma'_p$. This follows from $\Gamma_p \cong \pi_1(B - \{p\})$ and $\Gamma'_p \cong \pi_1(B' - \{p\})$, and the fact that B, B' are homeomorphic. So we shall denote $\Gamma'_p = \Gamma_p$ henceforth. We have the following result.

Theorem 3.1. *If one can arrange that the inclusions ι and ι' , given by (1) and (2), respectively, are such that $\iota = \iota'$ for every singular point $p \in S$, then there is a diffeomorphism $\tilde{X}_c \cong \tilde{X}_s$, which is the identity outside a small neighbourhood of the exceptional loci. In particular, \tilde{X}_c admits both complex and symplectic structures.*

Proof. The key point is obviously that if $\iota = \iota'$, then $Y' = Y$, so we can take $\tilde{Y}' = \tilde{Y}$ and $\pi' = \pi$ in the constructions above.

We fix a point $p \in S$, and construct the required isomorphism in a neighbourhood of the exceptional locus over that point. Consider the map (reducing $\epsilon > 0$ if necessary)

$$f = (\varphi'_p)^{-1} \circ \varphi_p: B_\epsilon(0) = \tilde{U}_p \rightarrow B_{\epsilon'}(0) = \tilde{U}'_p;$$

f is Γ_p -equivariant and an open embedding (it might fail to be surjective) with $f(0) = 0$. We shall construct a map $F: B_\epsilon(0) \rightarrow B_{\epsilon'}(0)$ such that

- $F = \mathrm{Id}$ in a small ball $B_{0.2\epsilon}(0)$,
- $F = f$ outside a slightly bigger ball $B_{0.9\epsilon}(0)$,
- F is a Γ_p -equivariant diffeomorphism onto its image.

This gives a diffeomorphism $F: \tilde{X}_c \rightarrow \tilde{X}_s$, defined by F on $B_\epsilon(0)/\Gamma_p - \{p\}$, extended by the identity on $\pi^{-1}(B_{0.2\epsilon}(0)/\Gamma_p)$, and also by the identity on $X - \pi^{-1}(B_{0.9\epsilon}(0)/\Gamma_p)$.

Write $f(x) = L(x) + R(x)$, where L is the linear part and $|R(x)| \leq C|x|^2$, for some constant $C > 0$. Both these maps are Γ_p -equivariant. Take a smooth, non-decreasing function $\rho_1: [0, \epsilon] \rightarrow [0, 1]$ such that $\rho_1(t) = 0$ for $t \in [0, 0.8\epsilon]$ and $\rho_1(t) = 1$ for $t \in [0.9\epsilon, 1]$. Consider $g(x) = L(x) + \rho_1(|x|)R(x)$. Then, $g(x) = L(x)$ for $|x| \leq 0.8\epsilon$, $g(x) = f(x)$ for $|x| \geq 0.9\epsilon$, and $g(x)$ is Γ_p -equivariant because $\Gamma_p \subset \mathrm{SO}(2n)$. Also

$$dg(x) - L = \rho'_1(|x|)R(x)d|x| + \rho_1(|x|)dR(x).$$

Using that $|\rho'_1(t)| \leq C/\epsilon$ and $|dR(x)| \leq C|x|$ (we denote by $C > 0$ uniform constants, that can vary from line to line) we have that $|dg(x) - L| \leq C|x|$. For $\epsilon > 0$ small enough, we have that g is a diffeomorphism onto its image.

For the next step, take the linear map $L: \mathbb{R}^{2n} \rightarrow \mathbb{R}^{2n}$. We can choose orthonormal (oriented) basis in both origin and target so that $L = \text{diag}(\lambda_1, \dots, \lambda_{2n})$, where $\lambda_i > 0$ are real numbers (the first vector of the basis is a unitary vector e_1 such that $|L(e_1)|$ is maximized; then L maps $\langle e_1 \rangle^\perp$ to $\langle L(e_1) \rangle^\perp$, and we proceed inductively). Consider the map

$$h(x) = \begin{cases} x, & |x| \leq 0.4\epsilon, \\ x + \rho_2 \left(\left(\frac{|x| - 0.4\epsilon}{0.3\epsilon} \right)^\alpha \right) (L(x) - x), & 0.4\epsilon \leq |x| \leq 0.7\epsilon, \\ g(x), & |x| \geq 0.7\epsilon, \end{cases}$$

where $\rho_2: [0, 1] \rightarrow [0, 1]$ is smooth non-decreasing with $\rho_2(t) = 0$ for $t \in [0, \frac{1}{3}]$, and $\rho_2(t) = 1$ for $t \in [\frac{2}{3}, 1]$. Here $\alpha > 0$ is a constant to be fixed soon.

Clearly h is Γ_p -equivariant, $h(x) = f(x)$ off $B_{0.9\epsilon}(0)$, and $h(x) = x$ in $B_{0.4\epsilon}(0)$ (but beware, we have chosen different coordinates on the origin \mathbb{R}^{2n} and the target \mathbb{R}^{2n} , so h is not the identity in the ball). The map h is C^∞ because for $0.4\epsilon \leq |x| \leq 0.5\epsilon$ we have also $h(x) = x$. Let us see that h is a diffeomorphism onto its image. It only remains to see this for $0.5\epsilon \leq |x| \leq 0.7\epsilon$. Write $y = h(x)$, so in our coordinates $y_i = x_i + \rho_2(u)(\lambda_i - 1)x_i$, with $u = \left(\frac{|x| - 0.4\epsilon}{0.3\epsilon} \right)^\alpha$. Then,

$$dy_i = (1 + (\lambda_i - 1)\rho_2(u)) dx_i + (\lambda_i - 1)\rho'_2(u) \frac{\alpha}{0.3\epsilon} \left(\frac{|x| - 0.4\epsilon}{0.3\epsilon} \right)^{\alpha-1} x_i \gamma$$

with $\gamma = d|x| = \frac{1}{|x|} \sum x_j dx_j$. Write $\delta_i = (1 + (\lambda_i - 1)\rho_2(u))$, so δ_i takes values between 1 and λ_i . We compute

$$\begin{aligned} dy_1 \wedge \dots \wedge dy_n &= \delta_1 \dots \delta_n dx_1 \wedge \dots \wedge dx_n + \\ &+ \sum \delta_1 \dots \hat{\delta}_i \dots \delta_n \frac{(\lambda_i - 1)\rho'_2(u)\alpha x_i}{0.3\epsilon} \left(\frac{|x| - 0.4\epsilon}{0.3\epsilon} \right)^{\alpha-1} dx_1 \wedge \dots \wedge \overset{(i)}{\gamma} \wedge \dots \wedge dx_n \\ &= \delta_1 \dots \delta_n \left(1 + \alpha \sum \frac{(\lambda_i - 1)\rho'_2(u)(|x| - 0.4\epsilon)^{\alpha-1} x_i^2}{|x|\delta_i(0.3\epsilon)^\alpha} \right) dx_1 \wedge \dots \wedge dx_n. \end{aligned}$$

In the sum, the numerator is bounded above by $C(0.3\epsilon)^{\alpha+1}$ and the denominator is bounded below by $C^{-1}(0.3\epsilon)^{\alpha+1}$, for some uniform (independent of α) constant $C > 0$. Hence choosing $\alpha > 0$ small enough, we get that the above quantity does not vanish, hence h is a diffeomorphism onto its image.

After this step is done, recall that we have taken coordinates given by an orthonormal basis $\{e_i\}$ on the origin \mathbb{R}^{2n} , and by the orthonormal basis $\{L(e_i)/\lambda_i\}$ on the target \mathbb{R}^{2n} . Written with respect to the same coordinates, we have an orthogonal transformation $M: \mathbb{R}^{2n} \rightarrow \mathbb{R}^{2n}$ so that $h(x) = M$ on $B_{0.4\epsilon}(0)$. The final step is to change the isometry $M \in \text{SO}(2n)$ by the identity. Take a smooth path M_t of matrices joining $M_0 = \text{Id}$ with $M_1 = M$. Take a smooth non-decreasing $\rho_3: [0, \epsilon] \rightarrow [0, 1]$ with $\rho_3(t) = 0$ for $t \in [0, 0.2\epsilon]$, and $\rho_3(t) = 1$ for $t \in [0.3\epsilon, \epsilon]$. The map $F(x) = M_{\rho_3(|x|)}(x)$, $|x| \leq 0.4\epsilon$, and $F(x) = h(x)$ for $|x| \geq 0.4\epsilon$, is the required map. \square

Remark 3.2. Let $F: (\tilde{X}_c, \tilde{J}) \rightarrow (\tilde{X}_s, \tilde{\omega})$ be the diffeomorphism provided by Theorem 3.1. Then if we denote $\tilde{\omega}' = F^*\tilde{\omega}$, we have that \tilde{X}_c admits a symplectic structure $\tilde{\omega}'$ and a complex

structure \tilde{J} . These are not compatible in general, but they are compatible on a neighbourhood of the exceptional locus, and give a Kähler structure there.

4. A COMPLEX AND SYMPLECTIC 6-ORBIFOLD

Consider the complex Heisenberg group G , that is, the complex nilpotent Lie group of (complex) dimension 3 consisting of matrices of the form

$$\begin{pmatrix} 1 & u_2 & u_3 \\ 0 & 1 & u_1 \\ 0 & 0 & 1 \end{pmatrix}.$$

In terms of the natural (complex) coordinate functions (u_1, u_2, u_3) on G , we have that the complex 1-forms $\mu = du_1$, $\nu = du_2$ and $\theta = du_3 - u_2 du_1$ are left invariant, and

$$d\mu = d\nu = 0, \quad d\theta = \mu \wedge \nu.$$

Let $\Lambda \subset \mathbb{C}$ be the lattice generated by 1 and $\zeta = e^{2\pi i/6}$, and consider the discrete subgroup $\Gamma \subset G$ formed by the matrices in which $u_1, u_2, u_3 \in \Lambda$. We define the compact (parallelizable) nilmanifold

$$M = \Gamma \backslash G.$$

We can describe M as a principal torus bundle

$$T^2 = \mathbb{C}/\Lambda \hookrightarrow M \rightarrow T^4 = (\mathbb{C}/\Lambda)^2$$

by the projection $(u_1, u_2, u_3) \mapsto (u_1, u_2)$.

Consider the action of the finite group \mathbb{Z}_6 on G given by the generator

$$\begin{aligned} \rho: G &\rightarrow G \\ (u_1, u_2, u_3) &\mapsto (\zeta^4 u_1, \zeta u_2, \zeta^5 u_3). \end{aligned}$$

This action satisfies that $\rho(p \cdot q) = \rho(p) \cdot \rho(q)$, for $p, q \in G$, where \cdot denotes the natural group structure of G . Moreover, $\rho(\Gamma) = \Gamma$. Thus, ρ induces an action on the quotient $M = \Gamma \backslash G$. Denote by $\rho: M \rightarrow M$ the \mathbb{Z}_6 -action. The action on 1-forms is given by

$$\rho^* \mu = \zeta^4 \mu, \quad \rho^* \nu = \zeta \nu, \quad \rho^* \theta = \zeta^5 \theta.$$

Proposition 4.1. $\widehat{M} = M/\mathbb{Z}_6$ is a 6-orbifold admitting complex and symplectic structures.

Proof. The nilmanifold M is a complex manifold whose complex structure J is the multiplication by i at each tangent space $T_p M$, $p \in M$. Then one can check that J commutes with the \mathbb{Z}_6 -action ρ on M , that is, $(\rho_*)_p \circ J_p = J_{\rho(p)} \circ (\rho_*)_p$, for any point $p \in M$. Hence, J induces a complex structure on the quotient $\widehat{M} = M/\mathbb{Z}_6$.

Now we define the complex 2-form ω on M given by

$$(3) \quad \omega = -i \mu \wedge \bar{\mu} + \nu \wedge \theta + \bar{\nu} \wedge \bar{\theta}.$$

Clearly, ω is a real closed 2-form on M which satisfies $\omega^3 > 0$, that is, ω is a symplectic form on M . Moreover, ω is \mathbb{Z}_6 -invariant. Indeed, $\rho^* \omega = -i \mu \wedge \bar{\mu} + \zeta^6 \nu \wedge \theta + \zeta^{-6} \bar{\nu} \wedge \bar{\theta} = \omega$. Therefore \widehat{M} is a symplectic 6-orbifold, with the symplectic form $\widehat{\omega}$ induced by ω . \square

We denote by

$$\widehat{\pi}: M \rightarrow \widehat{M}$$

the natural projection. The orbifold points of \widehat{M} are the following:

- (1) The points $(\frac{1}{3}a(1+\zeta), \frac{1}{3}b(1+\zeta), \frac{1}{3}c(1+\zeta) + \frac{2}{9}ab(1+\zeta)^2) \in M$, $a, b, c \in \{0, 1, 2\}$ and $(b, c) \neq (0, 0)$, are points of order 3, with isotropy group $K = \{\text{Id}, \rho^2, \rho^4\}$. These points are mapped in pairs by \mathbb{Z}_6 , so they define 12 orbifold points in $\widehat{M} = M/\mathbb{Z}_6$, with models \mathbb{C}^3/K .
- (2) The surfaces $S_{(p,q)} = \{(u_1, p, pu_1 + q) \mid u_1 \in \mathbb{C}/\Lambda\} \subset M$, where $p, q \in \{0, \frac{1}{2}, \frac{\zeta}{2}, \frac{1+\zeta}{2}\}$, $(p, q) \neq (0, 0)$. These are 15 tori, which consist of points of order 2, with isotropy $H = \{\text{Id}, \rho^3\}$. These surfaces are permuted by the group \mathbb{Z}_6 , so they come in 5 groups of three tori each. Thus they define 5 tori in the orbifold \widehat{M} , formed by orbifold points of order 2.
- (3) The surface $S_0 = \{(u_1, 0, 0) \mid u_1 \in \mathbb{C}/\Lambda\} \subset M$ is a torus consisting generically of points of order 2, with isotropy H . Here $\rho: S_0 \rightarrow S_0$ and it is a map of order 3, with three fixed points $(\frac{1}{3}a(1+\zeta), 0, 0)$, $a = 0, 1, 2$. These points have isotropy \mathbb{Z}_6 . The quotient $S_0/\langle\rho\rangle \subset \widehat{M}$ is homeomorphic to a sphere (with three orbifold points of order 3).

5. RESOLUTION OF THE 6-ORBIFOLD

Now we want to desingularize the orbifold \widehat{M} . We shall treat each of the connected components of the singular locus determined before independently. Recall that $K = \{\text{Id}, \rho^2, \rho^4\} \cong \mathbb{Z}_3$ and $H = \{\text{Id}, \rho^3\} \cong \mathbb{Z}_2$. There is a natural isomorphism $\langle\rho\rangle = \mathbb{Z}_6 \cong K \times H$.

5.1. Resolution of the isolated orbifold points. We know that there are 12 isolated orbifold points in \widehat{M} . Let $\widehat{p} \in \widehat{M}$ be one of them. The preimage of \widehat{p} under $\widehat{\pi}$ consists of two points, $\widehat{\pi}^{-1}(\widehat{p}) = \{p_1, p_2\}$. The isotropy group of p_1 is K . Consider a K -invariant neighbourhood U of p_1 in M . Then,

$$\widehat{U} = \widehat{\pi}(U) \cong U/K$$

is an orbifold neighbourhood of \widehat{p} in \widehat{M} . This has complex and symplectic resolutions as in Section 3. In order to apply Theorem 3.1 we check that $\iota = \iota': K \rightarrow \text{U}(3)$. For the complex resolution, we have $\iota(\zeta^2) = \text{diag}(\zeta^2, \zeta^2, \zeta^4)$. For the symplectic resolution, the symplectic form (3) is, in our coordinates (u_1, u_2, u_3) ,

$$(4) \quad \omega = -i du_1 \wedge d\bar{u}_1 + du_2 \wedge du_3 + d\bar{u}_2 \wedge d\bar{u}_3.$$

We have to do a change of variables to transform $K \subset \text{Sp}(6, \mathbb{R})$ into a subgroup of $\text{U}(3)$. This is obtained with

$$\begin{aligned} v_1 &= u_1 \\ v_2 &= \frac{1}{\sqrt{2}}(u_2 - i\bar{u}_3) \\ v_3 &= \frac{1}{\sqrt{2}}(\bar{u}_2 - iu_3). \end{aligned}$$

This transforms (4) into

$$\omega = -i dv_1 \wedge d\bar{v}_1 - i dv_2 \wedge d\bar{v}_2 - i dv_3 \wedge d\bar{v}_3,$$

the standard Kähler form. The K -action is given by $(v_1, v_2, v_3) \mapsto (\zeta^2 v_1, \zeta^2 v_2, \zeta^4 v_3)$, so $\iota'(\zeta^2) = \text{diag}(\zeta^2, \zeta^2, \zeta^4)$, and $\iota = \iota'$.

5.2. Resolution of the singular sets $\widehat{\pi}(S_{(p,q)})$. Now we consider a connected component of the singular set which is homeomorphic to a 2-torus. There are 5 such components in \widehat{M} , all of them are images by $\widehat{\pi}$ of the sets $S_{(p,q)} = \{(u_1, p, p u_1 + q) \mid u_1 \in \mathbb{C}/\Lambda\}$, where $(p, q) \in I = \left(\{0, \frac{1}{2}, \frac{\zeta}{2}, \frac{1+\zeta}{s}\}\right)^2 - \{(0, 0)\}$.

Let us focus on one such component $\widehat{T} = \widehat{\pi}(T)$, $T \cong \mathbb{C}/\Lambda$. Then H fixes $S_{(p,q)}$, and its orbit under K is given by $S_{(p_i, q_i)}$, for three elements $(p_1, q_1) = (p, q), (p_2, q_2), (p_3, q_3) \in I$. Consider a neighbourhood U of $T \subset M$ via

$$\begin{aligned} T \times B_\epsilon(0) &\rightarrow U \\ (u_1, u_2, u_3) &\mapsto (u_1, u_2 + p, u_3 + p u_1 + q), \end{aligned}$$

where $B_\epsilon(0) \subset \mathbb{C}^2$. The image is

$$(5) \quad \widehat{U} = \widehat{\pi}(U) \cong U/H \cong T \times (B_\epsilon(0)/H),$$

where $H \cong \mathbb{Z}_2$ acts as $(u_2, u_3) \mapsto (-u_2, -u_3)$.

We see that the complex structure on (5) is the product complex structure. Also, the symplectic structure $\omega = i du_1 \wedge d\bar{u}_1 + du_2 \wedge du_3 + d\bar{u}_2 \wedge d\bar{u}_3$ is the product of the natural symplectic structure of \mathbb{C}/Λ with an orbifold symplectic structure on $B_\epsilon(0)/H$. Using the construction of Section 3, we have a desingularization

$$\widetilde{Y} \rightarrow B_\epsilon(0)/H$$

which is a smooth manifold endowed with both a complex structure and a symplectic structure coinciding with the given ones outside a small neighbourhood of the exceptional locus E . The condition $\iota = \iota'$ of Theorem 3.1 is trivially satisfied, since $\iota(\rho^3) = \iota'(\rho^3) = -\text{Id}$. Multiplying by $T = \mathbb{C}/\Lambda$, we have that

$$\widetilde{U} = T \times \widetilde{Y}$$

is a smooth manifold endowed with a complex structure \widetilde{J} , and a symplectic structure $\widetilde{\omega}$, which coincide with those of \widehat{U} outside a small neighbourhood of the exceptional locus $T \times E \subset \widetilde{U}$.

The complex and the symplectic resolutions of \widehat{M} in a neighbourhood of \widehat{T} are obtained by replacing $\widehat{U} \subset \widehat{M}$ with \widetilde{U} . The two resolutions are diffeomorphic by the considerations above.

5.3. Resolution of the singular set $\widehat{\pi}(S_0)$. Finally we consider the connected component of the singular set which is homeomorphic to a 2-sphere. This is $\widehat{S}_0 = \widehat{\pi}(S_0)$, where $S_0 = \{(u_1, 0, 0) \mid u_1 \in \mathbb{C}/\Lambda\}$. As before, a neighbourhood of S_0 in M is of the form

$$U_0 = (\mathbb{C}/\Lambda) \times B_\epsilon(0),$$

where $B_\epsilon(0) \subset \mathbb{C}^2$. The action of $H = \mathbb{Z}_2$ is trivial on \mathbb{C}/Λ and as ± 1 on \mathbb{C}^2 . The action of $K = \mathbb{Z}_3$ is of the form $\rho^2(u_1, u_2, u_3) = (\zeta^2 u_1, \zeta^2 u_2, \zeta^4 u_3)$.

Let us focus on $B_\epsilon(0)/H$. By the construction of Section 3, we have a complex desingularization $(\widetilde{Y}_c, \widetilde{J}) \rightarrow B_\epsilon(0)/H$. The holomorphic action of K on $B_\epsilon(0)$ induces an action on $(\widetilde{Y}_c, \widetilde{J})$. Also, there is a symplectic desingularization $(\widetilde{Y}_s, \widetilde{\omega}) \rightarrow B_\epsilon(0)/H$. The action of K on $B_\epsilon(0)$ induces an action on $(\widetilde{Y}_s, \widetilde{\omega})$. This follows by taking an orbifold chart of the singular point that is $(H \times K)$ -equivariant, using the equivariant Darboux theorem.

By Theorem 3.1, there is a diffeomorphism $F: (\tilde{Y}_c, \tilde{J}) \rightarrow (\tilde{Y}_s, \tilde{\omega})$. Let us see that F can be taken to be K -equivariant. This follows by the arguments in the proof of Theorem 3.1 by using that $\iota: H \times K \rightarrow \mathrm{U}(2)$ and $\iota': H \times K \rightarrow \mathrm{U}(2)$ are equal. For the complex case, ι is given by the representation $(u_2, u_3) \mapsto (\zeta u_2, \zeta^5 u_3)$, so $\iota(\zeta) = \mathrm{diag}(\zeta, \zeta^5)$. For the symplectic case, we have to do a change of variables to transform $H \times K \subset \mathrm{Sp}(4, \mathbb{R})$ into a subgroup of $\mathrm{U}(2)$. This is given by

$$v_2 = \frac{1}{\sqrt{2}}(u_2 - i\bar{u}_3), \quad v_3 = \frac{1}{\sqrt{2}}(\bar{u}_2 - iu_3),$$

which transforms $\omega = du_2 \wedge du_3 + d\bar{u}_2 \wedge d\bar{u}_3$ into the standard Kähler form $-i dv_2 \wedge d\bar{v}_2 - i dv_3 \wedge d\bar{v}_3$. As $(v_2, v_3) \mapsto (\zeta v_2, \zeta^5 v_3)$, we have that $\iota'(\zeta) = \mathrm{diag}(\zeta, \zeta^5)$. Hence $\iota = \iota'$.

This produces a desingularization $\tilde{Y} \rightarrow B_\epsilon(0)/H$ with a symplectic and a complex structure, which match the given ones outside a small neighbourhood of the exceptional set $E \subset \tilde{Y}$, which are compatible (they give a Kähler structure) in a smaller neighbourhood of E , by Remark 3.2, and which have an action of K preserving both the complex and symplectic structures. A desingularization of

$$U_0/H = (\mathbb{C}/\Lambda) \times (B_\epsilon(0)/H)$$

is given by substituting a neighbourhood of $\hat{S}_0 = (\mathbb{C}/\Lambda) \times \{0\}$ by $(\mathbb{C}/\Lambda) \times \tilde{Y}$. The fixed points of action of K in U_0/H lie on \hat{S}_0 , hence the fixed points of the action of K on the desingularization of U_0/H lie in the exceptional divisor. In this part of the manifold, we have a Kähler structure, so the symplectic and complex desingularization are the same.

This means that $(U_0/H)/K \cong U_0/(H \times K)$ admits a desingularization \tilde{V} with a complex and a symplectic structure. The resolution of \widehat{M} in a neighbourhood of \hat{S}_0 is obtained by substituting $\hat{\pi}(U_0) = U_0/(H \times K) \subset \widehat{M}$ with \tilde{V} .

All together, we get a smooth 6-manifold \widetilde{M} with a complex structure and a symplectic structure, and with a map

$$\pi: \widetilde{M} \longrightarrow \widehat{M},$$

which is simultaneously a complex and a symplectic resolution.

6. TOPOLOGICAL PROPERTIES OF \widetilde{M}

In this section, we are going to complete the proof of Theorem 1.1 by proving that \widetilde{M} is simply-connected and that it does not admit a Kähler structure.

Proposition 6.1. *\widetilde{M} is simply connected.*

Proof. We fix base points $p_0 = (0, 0, 0) \in M$ and $\hat{p}_0 = \hat{\pi}(p_0) \in \widehat{M}$. There is an epimorphism of fundamental groups

$$\Gamma = \pi_1(M, p_0) \twoheadrightarrow \pi_1(\widehat{M}, \hat{p}_0),$$

since the \mathbb{Z}_6 -action has a fixed point [4, Chapter II, Corollary 6.3]. Now the nilmanifold M is a principal 2-torus bundle over the 4-torus T^4 , so we have an exact sequence

$$\mathbb{Z}^2 \hookrightarrow \Gamma \rightarrow \mathbb{Z}^4.$$

The group $\Gamma = \pi_1(M, p_0)$ is thus generated by the images of the fundamental groups of the surfaces $\Sigma_1 = \{(u_1, 0, 0)\}$, $\Sigma_2 = \{(0, u_2, 0)\}$ and $\Sigma_3 = \{(0, 0, u_3)\}$ in M . The image $\hat{\pi}(\Sigma_1)$ is a 2-sphere, since $\hat{\pi}: \Sigma_1 \rightarrow \hat{\pi}(\Sigma_1)$ is a degree 3 map with three ramification points

of order 3 (namely $(\frac{1}{2}a(1 + \zeta), 0, 0)$, with $a = 0, 1, 2$). The image of Σ_2 is also a 2-sphere, since $\widehat{\pi}: \Sigma_2 \rightarrow \widehat{\pi}(\Sigma_2)$ is a degree 6 map with one point of order 6, $(0, 0, 0)$, two of order 3, $(0, \frac{1}{2}b(1 + \zeta), 0)$, $b = 1, 2$, and three of order 2 (namely $(0, p, 0)$, $p = \frac{1}{2}, \frac{\zeta}{2}, \frac{1+\zeta}{2}$). Analogously, $\widehat{\pi}(\Sigma_3)$ is a 2-sphere. This proves that $\pi_1(\widehat{M}, \widehat{p}_0) = \{1\}$.

Now we look at the resolution process. Let $S \subset \widehat{M}$ be the singular locus and suppose $p \in S$ is an isolated orbifold point. The resolution replaces a neighbourhood $B = B_\epsilon(0)/\Gamma_p$ of p with a smooth manifold \widetilde{B} , such that $\pi: \widetilde{B} \rightarrow B$ is a complex resolution of singularities. The manifold \widetilde{B} is simply connected by [22, Theorem 4.1]. A Seifert-Van Kampen argument gives that $\pi_1(\widehat{M})$ is the amalgamated sum of $\pi_1(\widehat{M} - \{p\})$ and $\pi_1(B)$ along $\pi_1(\partial B)$. Also $\pi_1(\widehat{M})$ is the amalgamated sum of $\pi_1(\widehat{M} - E)$ and $\pi_1(\widetilde{B})$ along $\pi_1(\partial B)$. As $\pi_1(B) = \pi_1(\widetilde{B}) = \{1\}$, we have that $\pi_1(\widehat{M}) = \pi_1(\widetilde{M})$.

Suppose now that we have a connected component S' of the singular locus S of positive dimension. Let $E' = \pi^{-1}(S')$ be the corresponding exceptional locus. The invariance of the fundamental group under resolution is proved along the same lines as before if we know that the map $\pi: E' \rightarrow S'$ induces an isomorphism $\pi_1(E') \rightarrow \pi_1(S')$. In our case, we have two possibilities: if $S' = \widehat{\pi}(S_{(p,q)}) \cong T^2$, then $E' = T^2 \times E$, where E is the exceptional divisor of the resolution $\widetilde{Y} \rightarrow B_\epsilon(0)/H$, which is clearly simply connected, and the result follows.

The second possibility is $S' = \widehat{\pi}(S_0)$. In this case, the exceptional divisor over S' is the exceptional divisor of the resolution of

$$((\mathbb{C}/\Lambda) \times (\mathbb{C}^2/H))/K.$$

The resolution of \mathbb{C}^2/H is done by blowing-up \mathbb{C}^2 at the origin,

$$\widetilde{\mathbb{C}}^2 = \{(a, b, [u : v]) \in \mathbb{C}^2 \times \mathbb{C}\mathbb{P}^1 \mid av = bu\},$$

and then quotienting by $H = \{\pm \text{Id}\}$. Clearly, the fundamental groups of $(\mathbb{C}/\Lambda) \times (\mathbb{C}^2/H)$ and $(\mathbb{C}/\Lambda) \times (\widetilde{\mathbb{C}}^2/H)$ coincide. The action of K is given by $(a, b, [u : v]) \mapsto ((\zeta^2 a, \zeta^4 b), [u : \zeta^2 v])$, with fixed points $(0, 0, [1 : 0])$ and $(0, 0, [0 : 1])$. The fixed points of K on $((\mathbb{C}/\Lambda) \times (\widetilde{\mathbb{C}}^2/H))$ occur when K fixes both factors. Therefore, all fixed points are isolated, and the second resolution does not alter the fundamental group. \square

In order to prove that \widetilde{M} does not admit a Kähler structure, we are going to check that it does not satisfy the Lefschetz condition *for any symplectic form*. For this, it is necessary to understand the cohomology $H^*(\widetilde{M})$.

We start by computing the cohomology of \widehat{M} . By Nomizu theorem [18], the cohomology of the nilmanifold M is:

$$\begin{aligned} H^0(M, \mathbb{C}) &= \langle 1 \rangle, \\ H^1(M, \mathbb{C}) &= \langle [\mu], [\bar{\mu}], [\nu], [\bar{\nu}] \rangle, \\ H^2(M, \mathbb{C}) &= \langle [\mu \wedge \bar{\mu}], [\mu \wedge \bar{\nu}], [\bar{\mu} \wedge \nu], [\nu \wedge \bar{\nu}], [\mu \wedge \theta], [\bar{\mu} \wedge \bar{\theta}], [\nu \wedge \theta], [\bar{\nu} \wedge \bar{\theta}] \rangle, \\ H^3(M, \mathbb{C}) &= \langle [\mu \wedge \bar{\mu} \wedge \theta], [\mu \wedge \bar{\mu} \wedge \bar{\theta}], [\nu \wedge \bar{\nu} \wedge \theta], [\nu \wedge \bar{\nu} \wedge \bar{\theta}], [\mu \wedge \nu \wedge \theta], [\bar{\mu} \wedge \bar{\nu} \wedge \bar{\theta}], \\ &\quad [\mu \wedge \bar{\nu} \wedge \theta], [\mu \wedge \bar{\nu} \wedge \bar{\theta}], [\bar{\mu} \wedge \nu \wedge \theta], [\bar{\mu} \wedge \nu \wedge \bar{\theta}] \rangle, \\ H^4(M, \mathbb{C}) &= \langle [\mu \wedge \bar{\mu} \wedge \nu \wedge \theta], [\mu \wedge \bar{\mu} \wedge \bar{\nu} \wedge \bar{\theta}], [\bar{\mu} \wedge \nu \wedge \bar{\nu} \wedge \bar{\theta}], [\mu \wedge \nu \wedge \bar{\nu} \wedge \theta], \\ &\quad [\mu \wedge \bar{\mu} \wedge \theta \wedge \bar{\theta}], [\nu \wedge \bar{\nu} \wedge \theta \wedge \bar{\theta}], [\mu \wedge \bar{\nu} \wedge \theta \wedge \bar{\theta}], [\bar{\mu} \wedge \nu \wedge \theta \wedge \bar{\theta}] \rangle, \end{aligned}$$

$$\begin{aligned} H^5(M, \mathbb{C}) &= \langle [\mu \wedge \bar{\mu} \wedge \nu \wedge \theta \wedge \bar{\theta}], [\mu \wedge \bar{\mu} \wedge \bar{\nu} \wedge \theta \wedge \bar{\theta}], [\mu \wedge \nu \wedge \bar{\nu} \wedge \theta \wedge \bar{\theta}], [\bar{\mu} \wedge \nu \wedge \bar{\nu} \wedge \theta \wedge \bar{\theta}] \rangle, \\ H^6(M, \mathbb{C}) &= \langle [\mu \wedge \bar{\mu} \wedge \nu \wedge \bar{\nu} \wedge \theta \wedge \bar{\theta}] \rangle. \end{aligned}$$

So the cohomology $H^*(\widehat{M}) = H^*(M)^{\mathbb{Z}_6}$ of \widehat{M} is:

$$\begin{aligned} H^0(\widehat{M}, \mathbb{C}) &= \langle 1 \rangle, \\ H^1(\widehat{M}, \mathbb{C}) &= 0, \\ H^2(\widehat{M}, \mathbb{C}) &= \langle [\mu \wedge \bar{\mu}], [\nu \wedge \bar{\nu}], [\nu \wedge \theta], [\bar{\nu} \wedge \bar{\theta}] \rangle, \\ H^3(\widehat{M}, \mathbb{C}) &= 0, \\ H^4(\widehat{M}, \mathbb{C}) &= \langle [\mu \wedge \bar{\mu} \wedge \nu \wedge \theta], [\mu \wedge \bar{\mu} \wedge \bar{\nu} \wedge \bar{\theta}], [\mu \wedge \bar{\mu} \wedge \theta \wedge \bar{\theta}], [\nu \wedge \bar{\nu} \wedge \theta \wedge \bar{\theta}] \rangle, \\ H^5(\widehat{M}, \mathbb{C}) &= 0, \\ H^6(\widehat{M}, \mathbb{C}) &= \langle [\mu \wedge \bar{\mu} \wedge \nu \wedge \bar{\nu} \wedge \theta \wedge \bar{\theta}] \rangle. \end{aligned}$$

Proposition 6.2. \widetilde{M} does not admit a Kähler structure since it does not satisfy the Lefschetz property for any symplectic form on \widetilde{M} .

Proof. Let Ω be a symplectic form on \widetilde{M} . The Lefschetz map $L_{[\Omega]}: H^2(\widetilde{M}) \rightarrow H^4(\widetilde{M})$ is given by the cup product with $[\Omega]$. We show that there is a class $[\beta] \in H^2(\widetilde{M})$ which is in the kernel of $L_{[\Omega]}$. We prove this by checking that $[\Omega] \wedge [\beta] \wedge [\alpha] = 0$, for any 2-form $[\alpha] \in H^2(\widetilde{M})$.

We need to determine the cohomology $H^2(\widetilde{M})$. For this, the first step is to construct a map $H^2(\widehat{M}) \rightarrow H^2(\widetilde{M})$. Let $h: M \rightarrow M$ be a map which:

- is the identity outside small neighbourhoods of each point with non-trivial isotropy,
- contracts a neighbourhood of each of the isolated 24 points with isotropy K onto the corresponding point,
- contracts a neighbourhood of each $S_{(p,q)}$ onto $S_{(p,q)}$ (fixing $S_{(p,q)}$ pointwise),
- in a neighbourhood of S_0 , is the composition of a contraction onto S_0 with a map that contracts neighbourhoods (in S_0) of the 3 fixed points to the points, and
- is \mathbb{Z}_6 -equivariant.

h induces a map $\widehat{h}: \widehat{M} \rightarrow \widehat{M}$. Note that for any closed form $\alpha \in \Omega^*(\widehat{M})$, $\widehat{h}^*(\alpha) \in \Omega^*(\widehat{M})$ is cohomologous to α and can be lifted to a form $\pi^* \widehat{h}^*(\alpha) \in \Omega^*(\widetilde{M})$, where $\pi: \widetilde{M} \rightarrow \widehat{M}$ is the resolution map. This induces a well-defined map

$$\Psi = \pi^* \circ \widehat{h}^*: H^*(\widehat{M}) \rightarrow H^*(\widetilde{M}).$$

Now consider $U = \widehat{M} - S$, where $S \subset \widehat{M}$ is the singular locus and $V \subset \widehat{M}$ is a small neighbourhood of S . Let also $\widetilde{U} = \pi^{-1}(U)$ and $\widetilde{V} = \pi^{-1}(V) \subset \widetilde{M}$. Using compactly supported de Rham cohomology, we have a diagram

$$\begin{array}{ccccccc} H_c^2(U) \oplus H_c^2(V) & \rightarrow & H_c^2(\widehat{M}) & \rightarrow & H_c^3(U \cap V) & \rightarrow & H_c^3(U) \oplus H_c^3(V) \\ \downarrow = & \Psi \downarrow & \downarrow \Psi & & \downarrow \cong & & \downarrow = \Psi \downarrow \\ H_c^2(\widetilde{U}) \oplus H_c^2(\widetilde{V}) & \rightarrow & H_c^2(\widetilde{M}) & \rightarrow & H_c^3(\widetilde{U} \cap \widetilde{V}) & \rightarrow & H_c^3(\widetilde{U}) \oplus H_c^3(\widetilde{V}) \end{array}$$

Since V retracts onto a set of dimension 2, $H^3(V) = 0$. By Poincaré duality, $H_c^3(V) = 0$ as well. Now a simple diagram chasing proves that $H^2(\widetilde{M}) = H_c^2(\widetilde{M})$ is generated by $H^2(\widehat{M}) = H_c^2(\widehat{M})$ and $H_c^2(\widetilde{V})$.

Consider the closed form $\nu \wedge \bar{\nu} \in \Omega^2(\widehat{M})$. Since $\nu \wedge \bar{\nu}|_{S_{(p,q)}} = 0$ for any surface $S_{(p,q)}$ and $\nu \wedge \bar{\nu}|_{S_0} = 0$ as well, the 2-cohomology class

$$[\beta] = \Psi([\nu \wedge \bar{\nu}])$$

vanishes on \widetilde{V} . Clearly $[\beta] \wedge [\alpha_1] \wedge [\alpha_2] = 0$ if either $[\alpha_1], [\alpha_2] \in H_c^2(\widetilde{V})$. Moreover, one can check that $[\beta] \wedge [\alpha_1] \wedge [\alpha_2] = 0$, for $[\alpha_1], [\alpha_2] \in H^2(\widehat{M})$, which completes the proof. \square

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