

FRACTIONAL HARDY INEQUALITY WITH A REMAINDER TERM

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ABSTRACT. We prove a Hardy inequality for the fractional Laplacian on the interval with the optimal constant and additional lower order term. As a consequence, we also obtain a fractional Hardy inequality with the best constant and an extra lower order term for general domains, following the method of M. Loss and C. Sloane [16].

1. MAIN RESULT AND DISCUSSION

Recently Loss and Sloane [16] have proven the following fractional Hardy inequality

$$(1.1) \quad \frac{1}{2} \int_{D \times D} \frac{(u(x) - u(y))^2}{|x - y|^{n+\alpha}} dx dy \geq \kappa_{n,\alpha} \int_D \frac{u^2(x)}{\text{dist}(x, D^c)^\alpha} dx, \quad u \in C_c(D),$$

for convex domains $D \subset \mathbb{R}^n$ and $1 < \alpha < 2$, where

$$(1.2) \quad \kappa_{n,\alpha} = \pi^{\frac{n-1}{2}} \frac{\Gamma(\frac{1+\alpha}{2}) B(\frac{1+\alpha}{2}, \frac{2-\alpha}{2}) - 2^\alpha}{\Gamma(\frac{n+\alpha}{2}) \alpha 2^\alpha}$$

is the optimal constant. Here B is the Euler beta function, and $C_c(D)$ denotes the class of all continuous functions $u: \mathbb{R}^n \rightarrow \mathbb{R}$ with compact support in D . Inequality (1.1) with the optimal constant was earlier obtained for half-spaces and $\mathbb{R}^n \setminus \{0\}$, see [10, 11, 5, 9].

In this note we will prove the following strengthening of (1.1) for the interval.

Theorem 1.1. *Let $1 < \alpha < 2$, $-\infty < a < b < \infty$. For every $u \in C_c(a, b)$,*

$$(1.3) \quad \begin{aligned} \frac{1}{2} \int_a^b \int_a^b \frac{(u(x) - u(y))^2}{|x - y|^{1+\alpha}} dx dy &\geq \kappa_{1,\alpha} \int_a^b u^2(x) \left(\frac{1}{x-a} + \frac{1}{b-x} \right)^\alpha dx \\ &+ \frac{4 - 2^{3-\alpha}}{\alpha(b-a)} \int_a^b u^2(x) \left(\frac{1}{x-a} + \frac{1}{b-x} \right)^{\alpha-1} dx, \end{aligned}$$

and $\kappa_{1,\alpha}$ may not be replaced by a bigger constant in (1.3).

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For a domain $D \subset \mathbb{R}^n$ we consider a quadratic form

$$\mathcal{E}(u) = \frac{1}{2} \int_{D \times D} \frac{(u(x) - u(y))^2}{|x - y|^{n+\alpha}} dx dy, \quad u \in C_c(D).$$

By the method developed by Loss and Sloane in [16], from Theorem 1.1 one gets the fractional Hardy inequality with a *remainder* term for general domains, namely Theorem 1.2. To state the result we recall the notation from [16, 7]. Let $D \subset \mathbb{R}^n$ be a bounded domain. For a direction $w \in S^{n-1} = \{y \in \mathbb{R}^n : |y| = 1\}$ and $x \in D$ we define

$$\begin{aligned} d_{w,D}(x) &= \min\{|t| : x + tw \notin D\}, \\ \delta_{w,D}(x) &= \sup\{|t| : x + tw \in D\}, \end{aligned} \tag{1.4}$$

$$\frac{1}{M_\alpha(x)^\alpha} = \frac{\int_{S^{n-1}} \left[\frac{1}{d_{w,D}(x)} + \frac{1}{\delta_{w,D}(x)} \right]^\alpha dw}{\int_{S^{n-1}} |w_n|^\alpha dw} = \frac{\int_{S^{n-1}} \left[\frac{1}{d_{w,D}(x)} + \frac{1}{\delta_{w,D}(x)} \right]^\alpha dw}{2\kappa_{n,\alpha}/\kappa_{1,\alpha}}.$$

Theorem 1.2. *Let $1 < \alpha < 2$ and we let $D \subset \mathbb{R}^n$ be a bounded domain.*

We have

$$\mathcal{E}(u) \geq \kappa_{n,\alpha} \int_D \frac{u^2(x)}{M_\alpha(x)^\alpha} dx + \frac{\lambda_{n,\alpha}}{\text{diam } D} \int_D \frac{u^2(x)}{M_{\alpha-1}(x)^{\alpha-1}} dx, \quad u \in C_c(D), \tag{1.5}$$

where

$$\lambda_{n,\alpha} = \frac{\pi^{(n-1)/2} \Gamma(\frac{\alpha}{2}) (4 - 2^{3-\alpha})}{\alpha \Gamma(\frac{n+\alpha-1}{2})}.$$

In particular, if D is a bounded and convex domain, then

$$\mathcal{E}(u) \geq \kappa_{n,\alpha} \int_D \frac{u^2(x)}{\text{dist}(x, D^c)^\alpha} dx + \frac{\lambda_{n,\alpha}}{\text{diam } D} \int_D \frac{u^2(x)}{\text{dist}(x, D^c)^{\alpha-1}} dx, \quad u \in C_c(D). \tag{1.6}$$

Constant $\kappa_{n,\alpha}$ in (1.5) and (1.6) may not be replaced by a bigger constant.

The above theorem is a strengthening of [16, Theorem 1.1]. The main difference is the remainder term in (1.5) and (1.6), under the additional assumption that the domain is bounded. We like to note that for cones (e.g., $\mathbb{R}^n \setminus \{0\}$) there is no remainder term of the form (1.6). We consider the dilations of u and see that the homogeneity of $\mathcal{E}(u)$ and the term $\int_D \frac{u^2(x)}{\text{dist}(x, D^c)^\alpha} dx$ is the same, but different from that of $\int_D \frac{u^2(x)}{\text{dist}(x, D^c)^{\alpha-1}} dx$.

As a consequence of Theorem 1.2 we may obtain estimates for the first eigenvalue of regional fractional Laplacian, see e.g. [15], or [14] for other applications of Hardy inequalities.

We denote

$$Lu(x) = \lim_{\varepsilon \rightarrow 0^+} \int_{(-1,1) \cap \{|y-x| > \varepsilon\}} \frac{u(y) - u(x)}{|x - y|^{1+\alpha}} dy,$$

L is, up to a multiplicative constant, the regional fractional Laplacian [13]. We calculate Lw for the function $w(x) = (1 - x^2)^{(\alpha-1)/2}$, see Lemma 2.1, and the result follows from the ideas of [1, 8], see also [9, Proposition 2.3] or Lemma 2.2 below. We like to note that the calculation of Lw is done by using the Kelvin transform. For a discussion on the Kelvin transform and the fractional Laplacian we refer the reader to [6].

We note that the explicit formula for $Lu_p(x)$, where $u_p(x) = (1 - x^2)^p$, may be deduced from [12] for $p = \alpha/2$, and for $p = \frac{\alpha-2}{2}$ from [2]. See the remarks after the proof of Lemma 2.1.

Finally, let us note that the symmetric bilinear form obtained from \mathcal{E} by polarisation is, up to a multiplicative constant, the Dirichlet form of the censored stable process in $(-1, 1)$, see [3]. The following result is a counterpart of Lemma 2.3 and Theorem 1.1 corresponding to a killed stable process [3] and it turns out to have a simple form.

Corollary 1.3. *Let $0 < \alpha < 2$ and $w(x) = (1 - x^2)^{(\alpha-1)/2}$. For every $u \in C_c(-1, 1)$*

$$\begin{aligned}
 \frac{1}{2} \int_{\mathbb{R}} \int_{\mathbb{R}} \frac{(u(x) - u(y))^2}{|x - y|^{1+\alpha}} dx dy &= \frac{1}{2} \int_{-1}^1 \int_{-1}^1 \left(\frac{u(x)}{w(x)} - \frac{u(y)}{w(y)} \right)^2 \frac{w(x)w(y)}{|x - y|^{1+\alpha}} dx dy \\
 &\quad + \frac{B(\frac{1+\alpha}{2}, \frac{2-\alpha}{2})}{\alpha} \int_{-1}^1 u^2(x) (1 - x^2)^{-\alpha} dx \\
 (1.7) \qquad \qquad \qquad &\geq \frac{B(\frac{1+\alpha}{2}, \frac{2-\alpha}{2})}{\alpha 2^\alpha} \int_{-1}^1 u^2(x) \left(\frac{1}{x+1} + \frac{1}{1-x} \right)^\alpha dx.
 \end{aligned}$$

The constant $\frac{B(\frac{1+\alpha}{2}, \frac{2-\alpha}{2})}{\alpha 2^\alpha}$ in the above inequality may not be replaced by a bigger one.

2. PROOFS

We start by calculating the regional fractional Laplacian on power functions.

Lemma 2.1. *Let $p > -1$ and $u_p(x) = (1 - x^2)^p$. For $0 < \alpha < 2$ we have*

$$\begin{aligned}
 Lu_p(x) &= \frac{(1 - x^2)^{p-\alpha}}{\alpha} \left((1 - x)^\alpha + (1 + x)^\alpha \right. \\
 (2.1) \qquad &\quad \left. - (2p + 2 - \alpha)B(p + 1, 1 - \alpha/2) + \alpha I(p) \right),
 \end{aligned}$$

where

$$I(p) = p.v. \int_{-1}^1 \frac{(1 - tx)^{\alpha-1-2p} - 1}{|t|^{1+\alpha}} (1 - t^2)^p dt.$$

We have $I(\frac{\alpha}{2}) = \frac{2}{\alpha}B(1 + \frac{\alpha}{2}, 1 - \frac{\alpha}{2})(1 - (1 - x^2)^{\alpha/2})$, $I(\frac{\alpha-1}{2}) = I(\frac{\alpha-2}{2}) = 0$, and if $1 < \alpha < 2$, then $I(\frac{\alpha-3}{2}) = x^2B(\frac{\alpha-1}{2}, 1 - \alpha/2)$.

Proof. By changing variable $t = y^2$ and integrating by parts, we have

$$\begin{aligned} Lu_p(0) &= 2 \lim_{\varepsilon \rightarrow 0^+} \int_{\varepsilon}^1 \frac{(1 - y^2)^p - 1}{y^{1+\alpha}} dy \\ &= 2 \lim_{\varepsilon \rightarrow 0^+} \left(\frac{1}{2} \int_{\varepsilon^2}^1 (1 - t)^p t^{-1-\alpha/2} [(1 - t) + t] dt - \int_{\varepsilon}^1 y^{-1-\alpha} dy \right) \\ &= 2 \lim_{\varepsilon \rightarrow 0^+} \left(\frac{1}{\alpha} (1 - \varepsilon^2)^{p+1} \varepsilon^{-\alpha} - \frac{p+1}{\alpha} \int_{\varepsilon^2}^1 (1 - t)^p t^{-\alpha/2} dt \right. \\ &\quad \left. + \frac{1}{2} \int_{\varepsilon^2}^1 (1 - t)^p t^{-\alpha/2} dt + \frac{1}{\alpha} - \frac{\varepsilon^{-\alpha}}{\alpha} \right). \end{aligned}$$

It is easy to see that

$$\lim_{\varepsilon \rightarrow 0^+} \left(\frac{1}{\alpha} (1 - \varepsilon^2)^{p+1} \varepsilon^{-\alpha} - \frac{\varepsilon^{-\alpha}}{\alpha} \right) = \lim_{\varepsilon \rightarrow 0^+} \frac{\varepsilon^{2-\alpha}}{\alpha} \frac{(1 - \varepsilon^2)^{p+1} - 1}{\varepsilon^2} = 0.$$

Hence

$$Lu_p(0) = \frac{2}{\alpha} [1 - (p+1 - \alpha/2)B(p+1, 1 - \alpha/2)].$$

For $x_0 \in (-1, 1)$ we have

$$Lu_p(x_0) = p.v. \int_{-1}^1 \frac{(1 - y^2)^p - (1 - x_0^2)^p}{|y - x_0|^{1+\alpha}} dy.$$

We change the variable in the following way

$$\begin{aligned} t = \varphi(y) &= \frac{x_0 - y}{1 - x_0 y}, & y = \varphi(t), & \text{ then} \\ \varphi'(y) &= \frac{x_0^2 - 1}{(1 - x_0 y)^2}, & y - x_0 &= \frac{t(1 - x_0^2)}{tx_0 - 1}, & 1 - y^2 &= \frac{(1 - x_0^2)(1 - t^2)}{(tx_0 - 1)^2}. \end{aligned}$$

The principal value integral transforms as follows

$$\begin{aligned} (2.2) \quad Lu_p(x_0) &= (1 - x_0^2)^{p-\alpha} p.v. \int_{-1}^1 \frac{(1 - t^2)^p - (1 - tx_0)^{2p}}{|t|^{1+\alpha}} (1 - tx_0)^{\alpha-1-2p} dt \\ &= (1 - x_0^2)^{p-\alpha} \left[Lu_p(0) - p.v. \int_{-1}^1 \frac{(1 - tx_0)^{\alpha-1} - 1}{|t|^{1+\alpha}} dt \right. \\ &\quad \left. + p.v. \int_{-1}^1 \frac{(1 - tx_0)^{\alpha-1-2p} - 1}{|t|^{1+\alpha}} (1 - t^2)^p dt \right]. \end{aligned}$$

We consider the integral in (2.2),

$$I = p.v. \int_{-1}^1 \frac{(1 - tx_0)^{\alpha-1} - 1}{|t|^{1+\alpha}} dt = \lim_{\varepsilon \rightarrow 0^+} (J_{\varepsilon}(x_0) + J_{\varepsilon}(-x_0)),$$

where

$$\begin{aligned} J_\varepsilon(x_0) &= \int_\varepsilon^1 \frac{(1-tx_0)^{\alpha-1} - 1}{t^{1+\alpha}} dt = \int_\varepsilon^1 \left(\frac{1}{t} - x_0\right)^{\alpha-1} \frac{dt}{t^2} - \frac{\varepsilon^{-\alpha} - 1}{\alpha} \\ &= \frac{1}{\alpha} \left(\frac{1}{\varepsilon} - x_0\right)^\alpha - \frac{1}{\alpha} (1-x_0)^\alpha - \frac{\varepsilon^{-\alpha} - 1}{\alpha} \\ &= \frac{1}{\alpha} - \frac{1}{\alpha} (1-x_0)^\alpha + \frac{(1-\varepsilon x_0)^\alpha - 1}{\alpha \varepsilon^\alpha}. \end{aligned}$$

By l'Hôpital rule we find out that

$$I = \frac{2}{\alpha} - \frac{1}{\alpha} (1-x_0)^\alpha - \frac{1}{\alpha} (1+x_0)^\alpha,$$

and the first part of the lemma is proved.

We have

$$\begin{aligned} I(\alpha/2) &= p.v. \int_{-1}^1 \frac{(1-tx)^{-1} - 1}{|t|^{1+\alpha}} (1-t^2)^{\alpha/2} dt \\ &= \int_{-1}^1 \frac{\sum_{k=2}^{\infty} (tx)^k}{|t|^{1+\alpha}} (1-t^2)^{\alpha/2} dt = 2 \int_0^1 \frac{\sum_{k=1}^{\infty} (tx)^{2k}}{|t|^{1+\alpha}} (1-t^2)^{\alpha/2} dt \\ &= \sum_{k=1}^{\infty} B\left(k - \frac{\alpha}{2}, 1 + \frac{\alpha}{2}\right) x^{2k} \\ &= \Gamma\left(1 + \frac{\alpha}{2}\right) \Gamma\left(\frac{-\alpha}{2}\right) \left(\sum_{k=0}^{\infty} \frac{x^{2k} \Gamma\left(k - \frac{\alpha}{2}\right)}{\Gamma\left(\frac{-\alpha}{2}\right) k!} - 1 \right) \\ &= \frac{2B\left(1 + \frac{\alpha}{2}, 1 - \frac{\alpha}{2}\right)}{\alpha} \left(1 - (1-x^2)^{\alpha/2}\right). \end{aligned}$$

Calculating $I(p)$ for $p = \frac{\alpha-1}{2}$, $p = \frac{\alpha-2}{2}$ and $p = \frac{\alpha-3}{2}$ is easy and will be omitted. \square

In the sequel we will need the above lemma only for $p = \frac{\alpha-1}{2}$. The fractional Laplacian on $u_{\alpha/2}$, extended to be zero on $\mathbb{R} \setminus (-1, 1)$, was calculated by using Fourier transform and hypergeometric function in [12]. From those calculations we may confirm our formula for $Lu_{\alpha/2}$ and, consequently, for $I(\alpha/2)$. Also the value of $Lu_{(\alpha-2)/2}$ can be calculated from known results. Namely, $u_{(\alpha-2)/2}(x) = \frac{1}{2}(K(x, -1) + K(x, 1))$ for $|x| < 1$, where $K(x, Q) = \frac{(1-x^2)^{\alpha/2}}{|x-Q|}$ is the Martin kernel for the interval [2, (3.36)]. Hence $u_{(\alpha-2)/2}(x)$ extended to be zero on $\mathbb{R} \setminus (-1, 1)$ annihilates on $(-1, 1)$ the fractional Laplacian, see also [4, Chapter 3] and [3, (3.14)].

The next lemma may be considered a special case of Proposition 2.3 from [9], see also [8]. For reader's convenience we give an elementary proof following [5].

Lemma 2.2. *Let $D \subset \mathbb{R}^n$ be an open set. For every $u \in C_c(D)$ and any strictly positive function $w \in C^2(D) \cap L^1(D, (1 + |x|)^{-n-\alpha} dx)$, we have*

$$\mathcal{E}(u) = \int_D u^2(x) \frac{-Lw(x)}{w(x)} dx + \frac{1}{2} \int_D \int_D \left(\frac{u(x)}{w(x)} - \frac{u(y)}{w(y)} \right)^2 \frac{w(x)w(y)}{|x-y|^{n+\alpha}} dx dy.$$

Proof. We have

$$\begin{aligned} (u(x) - u(y))^2 + u^2(x) \frac{w(y) - w(x)}{w(x)} + u^2(y) \frac{w(x) - w(y)}{w(y)} \\ = \left(\frac{u(x)}{w(x)} - \frac{u(y)}{w(y)} \right)^2 w(x)w(y). \end{aligned}$$

We integrate against $1_{\{|x-y|>\varepsilon\}} |x-y|^{-n-\alpha} dx dy$, and let $\varepsilon \rightarrow 0$. We can use Taylor's expansion for w and the compactness of the support of u to justify the application of Lebesgue dominated convergence theorem. \square

We next state a result analogous to the ground state representation obtained for half-spaces and $\mathbb{R}^n \setminus \{0\}$ by Frank and Seiringer [9, 11]. In the following result we return to $D = (-1, 1)$ and $n = 1$.

Lemma 2.3. *Let $0 < \alpha < 2$. Let $w(x) = (1 - x^2)^{(\alpha-1)/2}$. For every $u \in C_c(-1, 1)$,*

$$\begin{aligned} \mathcal{E}(u) &= \frac{1}{2} \int_{-1}^1 \int_{-1}^1 \left(\frac{u(x)}{w(x)} - \frac{u(y)}{w(y)} \right)^2 \frac{w(x)w(y)}{|x-y|^{1+\alpha}} dx dy \\ &\quad + 2^\alpha \kappa_{1,\alpha} \int_{-1}^1 u^2(x) (1 - x^2)^{-\alpha} dx \\ &\quad + \frac{1}{\alpha} \int_{-1}^1 u^2(x) [2^\alpha - (1+x)^\alpha - (1-x)^\alpha] (1 - x^2)^{-\alpha} dx. \end{aligned}$$

Proof of Lemma 2.3. The lemma follows immediately from Lemma 2.2 applied to $w(x) = (x^2 - 1)^{(\alpha-1)/2}$ and Lemma 2.1 with $p = (\alpha - 1)/2$. \square

Proof of Theorem 1.1. By scaling we may and do assume that $a = -1$ and $b = 1$. By Lemma 2.3 it is enough to verify that

$$(2.3) \quad 2^\alpha - (1+x)^\alpha - (1-x)^\alpha \geq (2^\alpha - 2)(1 - x^2), \quad 1 \leq \alpha \leq 2, \quad 0 \leq x \leq 1.$$

Substituting $u = x^2$, it is enough to verify that

$$g(u) = (2^\alpha - 2)u - (1 - \sqrt{u})^\alpha - (1 + \sqrt{u})^\alpha + 2$$

is concave, or

$$g'(u) = 2^\alpha - 2 + \frac{\alpha}{2\sqrt{u}} \left((1 - \sqrt{u})^{\alpha-1} - (1 + \sqrt{u})^{\alpha-1} \right)$$

is decreasing. We substitute $u = t^2$ and observe that

$$\frac{(1-t)^{\alpha-1} - (1+t)^{\alpha-1}}{t} = \frac{h(t) - h(0)}{t},$$

where $h(t) = (1-t)^{\alpha-1} - (1+t)^{\alpha-1}$. Since h is concave, the function $t \mapsto \frac{h(t)-h(0)}{t}$ is decreasing, and so is g' . This proves (2.3), and (1.3).

The fact that $\kappa_{1,\alpha}$ in (1.3) is optimal follows from [5]. \square

The constant $2^\alpha - 2$ in (2.3) is the largest possible, consider $x = 0$. However it is not clear if the constant $\frac{4-2^{3-\alpha}}{\alpha(b-a)}$ is optimal in (1.3).

Proof of Theorem 1.2. The proof is analogous to the proof of Theorem 1.1 in [16], but instead of applying [16, Corollary 2.3] we use Theorem 1.1. For reader's convenience we repeat the beginning of the argument of Loss and Sloane. By [16, Lemma 2.4] and [16, Corollary 2.3] we find that

$$\begin{aligned}
 \mathcal{E}(u) &= \frac{1}{4} \int_{S^{n-1}} dw \int_{\{x:x \cdot w=0\}} d\mathcal{L}_w(x) \int_{x+sw \in D} ds \int_{x+tw \in D} dt \frac{|u(x+sw) - u(x+tw)|^2}{|s-t|^{1+\alpha}} \\
 &\geq \kappa_{1,\alpha} \frac{1}{2} \int_{S^{n-1}} dw \int_{\{x:x \cdot w=0\}} d\mathcal{L}_w(x) \int_{x+sw \in D} ds |u(x+sw)|^2 \\
 &\quad \times \left[\frac{1}{d_w(x+sw)} + \frac{1}{\delta_w(x+sw)} \right]^\alpha \\
 &+ \frac{4-2^{3-\alpha}}{2\alpha} \int_{S^{n-1}} dw \int_{\{x:x \cdot w=0\}} d\mathcal{L}_w(x) \int_{x+sw \in D} ds |u(x+sw)|^2 \\
 &\quad \times \left[\frac{1}{d_w(x+sw)} + \frac{1}{\delta_w(x+sw)} \right]^{\alpha-1} \frac{1}{d_w(x+sw) + \delta_w(x+sw)} \\
 &= \kappa_{1,\alpha} \frac{1}{2} \int_{S^{n-1}} dw \int_D |u(x)|^2 \left[\frac{1}{d_{w,D}(x)} + \frac{1}{\delta_{w,D}(x)} \right]^\alpha dx \\
 &+ \frac{4-2^{3-\alpha}}{2\alpha} \int_{S^{n-1}} dw \int_D |u(x)|^2 \left[\frac{1}{d_{w,D}(x)} + \frac{1}{\delta_{w,D}(x)} \right]^{\alpha-1} \frac{1}{d_{w,D}(x) + \delta_{w,D}(x)} dx \\
 &\geq \kappa_{n,\alpha} \int_D \frac{|u(x)|^2}{M_\alpha(x)^\alpha} dx + \frac{\lambda_{n,\alpha}}{\text{diam } D} \int_D \frac{|u(x)|^2}{M_{\alpha-1}(x)^{\alpha-1}} dx.
 \end{aligned}$$

In the last line we have used [16, (7)], which is valid for any $\alpha > 0$, hence also for $\alpha - 1$ in place of α . This proves (1.5).

Inequality (1.6) follows from [16, (9)], which is also valid for any $\alpha > 0$. \square

Proof of Corollary 1.3. The equality follows from Lemma 2.3 and the following formula, where we take $D = (-1, 1)$ in the definition of $\mathcal{E}(u)$

$$\begin{aligned}
 \frac{1}{2} \int_{\mathbb{R}} \int_{\mathbb{R}} \frac{(u(x) - u(y))^2}{|x-y|^{1+\alpha}} dx dy &= \mathcal{E}(u) + \int_{-1}^1 u^2(x) \frac{(1+x)^{-\alpha} + (1-x)^{-\alpha}}{\alpha} dx \\
 &= \frac{1}{2} \int_{-1}^1 \int_{-1}^1 \left(\frac{u(x)}{w(x)} - \frac{u(y)}{w(y)} \right)^2 \frac{w(x)w(y)}{|x-y|^{1+\alpha}} dx dy \\
 (2.4) \quad &+ \frac{2^\alpha(\kappa_{1,\alpha} + \alpha)}{\alpha} \int_{-1}^1 u^2(x) (1-x^2)^{-\alpha} dx.
 \end{aligned}$$

□

The sharpness of the constant $\frac{B(\frac{1+\alpha}{2}, \frac{2-\alpha}{2})}{\alpha 2^\alpha}$ in (1.7) follows from [5].

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